

Absolute encoders – multiturn

Standard mechanical multiturn, optical	Sendix 5863 / 5883 (shaft / hollow shaft)	SSI / BiSS
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The Sendix 5863 and 5883 multiturn encoders with SSI or BiSS interface and optical sensor technology can achieve a resolution of max. 29 bits.

A through hollow shaft up to 14 mm and a blind hollow shaft up to 15 mm are available, as well as versions with additional SinCos or RS422 incremental track.



Mechanical drive	Safety-Lock™	High rotational speed	Temperature range	High protection level	High shaft load capacity	Shock / vibration resistant	Magnetic field proof	Reverse polarity protection	SinCos	Surface protection salt spray-tested optional

Reliable

- Tried-and-tested in applications with the highest demands, such as in wind energy or mobile automation.
- Absolutely reliable operation in areas with strong magnetic fields, thanks to mechanical gear with optical sensor technology.
- Rugged die-cast housing, remains sealed even in harsh everyday use.
- -40°C... +90°C: use in wide temperature range and protection IP67.

Versatile

- Available with SSI or BiSS interface and combined with SinCos incremental signals.
- The right fixing solution or type of connection available for every application.
- SET button and LED for simple start-up.

Absolute encoders multiturn

Order code

Shaft version

8.5863	.	XXXX	.	XX2X
Type		a b c d		e f g h

If for each parameter of an encoder the underlined preferred option is selected, then the delivery time will be 10 working days for a maximum of 10 pieces. Qts. up to 50 pcs. of these types generally have a delivery time of 15 working days.



a Flange

- 1 = clamping flange, IP65 ø 58 mm [2.28"]**
- 3 = clamping flange, IP67 ø 58 mm [2.28"]
- 2 = synchro flange, IP65 ø 58 mm [2.28"]**
- 4 = synchro flange, IP67 ø 58 mm [2.28"]
- 5 = square flange, IP65 □ 63.5 mm [2.5"]
- 7 = square flange, IP67 □ 63.5 mm [2.5"]

- 6 = servo flange, IP65 ø 63.5 mm [2.5"] ¹⁾
- 8 = servo flange, IP67 ø 63.5 mm [2.5"] ¹⁾

b Shaft (ø x L), with flat

- 1 = 6 x 10 mm [0.24 x 0.39"]** ²⁾
- 2 = 10 x 20 mm [0.39 x 0.79"]** ³⁾
- 3 = 1/4" x 7/8"
- 4 = 3/8" x 7/8"

c Interface / power supply

- 1 = SSI, BiSS / 5 V DC
- 2 = SSI, BiSS / 10 ... 30 V DC**
- 3 = SSI, BiSS + 2048 ppr. SinCos / 5 V DC
- 4 = SSI, BiSS + 2048 ppr. SinCos / 10 ... 30 V DC
- 5 = SSI, BiSS / 5 V DC, with sensor output
- 6 = SSI, BiSS + 2048 ppr. SinCos / 5 V DC, with sensor output
- 7 = SSI, BiSS + 2048 ppr. RS422 (TTL-comp.) / 5 V DC
- 8 = SSI, BiSS + 2048 ppr. RS422 (TTL-comp.) / 10 ... 30 V DC
- 9 = SSI, BiSS + 2048 ppr. RS422 (TTL-comp.) / 5 V DC, with sensor output

d Type of connection

- 1 = axial cable, 1 m [3.28"] PVC
- A = axial cable, special length PVC *)
- 2 = radial cable, 1 m [3.28"] PVC**
- B = radial cable, special length PVC *)
- 3 = axial M23 connector, 12-pin
- 4 = radial M23 connector, 12-pin**
- 5 = axial M12 connector, 8-pin ⁴⁾
- 6 = radial M12 connector, 8-pin ⁴⁾

*) Available special lengths (connection types A, B):
2, 3, 5, 8, 10, 15 m [5.56, 9.84, 16.40, 26.25, 32.80, 49.21"]
order code expansion .XXXX = length in dm
ex.: 8.5863.112A.G323.0030 (for cable length 3 m)

e Code

- B = SSI, binary
- C = BiSS, binary
- G = SSI, gray**

f Resolution ⁵⁾

- A = 10 bit ST + 12 bit MT
- 1 = 11 bit ST + 12 bit MT
- 2 = 12 bit ST + 12 bit MT
- 3 = 13 bit ST + 12 bit MT**
- 4 = 14 bit ST + 12 bit MT
- 7 = 17 bit ST + 12 bit MT

Optional on request

- Ex 2/22 ⁶⁾
- surface protection salt spray tested
- other singleturn resolutions

g Inputs / outputs ⁵⁾

- 2 = SET, DIR input**
- additional status output

h Options (service)

- 1 = no option
- 2 = status LED
- 3 = SET button and status LED**

1) US version.

2) Preferred type only in conjunction with flange type 2.

3) Preferred type only in conjunction with flange type 1.

4) Only in conjunction with interface type 1 and 2.

5) Resolution, preset value and counting direction factory-programmable.

6) For the cable connection type, cable material PUR.

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Order code	8.5883	XXXX	XX2X	<p>If for each parameter of an encoder the underlined preferred option is selected, then the delivery time will be 10 working days for a maximum of 10 pieces. Qts. up to 50 pcs. of these types generally have a delivery time of 15 working days.</p>
Hollow shaft	Type	a b c d	e f g h	
<p>a Flange 1 = with spring element, long, IP65 2 = with spring element, long, IP67 3 = with stator coupling, IP65 ø 65 mm [2.56"] 4 = with stator coupling, IP67 ø 65 mm [2.56"] <u>5 = with stator coupling, IP65 ø 63 mm [2.48"]</u> 6 = with stator coupling, IP67 ø 63 mm [2.48"]</p> <p>b Hollow shaft 3 = ø 10 mm [0.39"] <u>4 = ø 12 mm [0.47"]</u> 5 = ø 14 mm [0.55"] 6 = ø 15 mm [0.59"] – blind hollow shaft 8 = ø 3/8" 9 = ø 1/2"</p> <p>c Interface / power supply 1 = SSI, BiSS / 5 V DC <u>2 = SSI, BiSS / 10 ... 30 V DC</u> 3 = SSI, BiSS + 2048 ppr. SinCos / 5 V DC 4 = SSI, BiSS + 2048 ppr. SinCos / 10 ... 30 V DC 5 = SSI, BiSS / 5 V DC, with sensor output 6 = SSI, BiSS + 2048 ppr. SinCos / 5 V DC, with sensor output 7 = SSI, BiSS + 2048 ppr. RS422 (TTL-comp.) / 5 V DC 8 = SSI, BiSS + 2048 ppr. RS422 (TTL-comp.) / 10 ... 30 V DC 9 = SSI, BiSS + 2048 ppr. RS422 (TTL-comp.) / 5 V DC, with sensor output</p> <p>d Type of connection 2 = radial cable, 1 m [3.28'] PVC B = radial cable, special length PVC *) <u>E = tangential cable, 1 m [3.28'] PVC</u> F = tangential cable, special length PVC *) <u>4 = radial M23 connector, 12-pin</u> 6 = radial M12 connector, 8-pin ²⁾</p> <p>*) Available special lengths (connection types B, F): 2, 3, 5, 8, 10, 15 m [5.56, 9.84, 16.40, 26.25, 32.80, 49.21'] order code expansion .XXXX = length in dm ex.: 8.5883.542B.G323.0030 (for cable length 3 m)</p> <p>e Code B = SSI, binary C = BiSS, binary <u>G = SSI, gray</u></p> <p>f Resolution ¹⁾ A = 10 bit ST + 12 bit MT 1 = 11 bit ST + 12 bit MT 2 = 12 bit ST + 12 bit MT <u>3 = 13 bit ST + 12 bit MT</u> 4 = 14 bit ST + 12 bit MT 7 = 17 bit ST + 12 bit MT</p> <p>g Inputs / outputs ¹⁾ <u>2 = SET, DIR input</u> additional status output</p> <p>h Options (service) 1 = no option 2 = status LED <u>3 = SET button and status LED</u></p> <p style="text-align: right;"><i>Optional on request</i> - Ex 2/22 (not for type of connection E, F) ³⁾ - surface protection salt spray tested - other singleturn resolutions</p>				

Mounting accessory for shaft encoders	Order no.
Coupling	
bellows coupling ø 19 mm [0.75"] for shaft 6 mm [0.24"]	8.0000.1102.0606
bellows coupling ø 19 mm [0.75"] for shaft 10 mm [0.39"]	8.0000.1102.1010
Mounting accessory for hollow shaft encoders	Order no.
Cylindrical pin, long	
for torque stops	
	8.0010.4700.0000
Connection technology	Order no.
Connector, self-assembly (straight)	
M12 female connector with coupling nut	05.CMB 8181-0
M23 female connector with coupling nut	8.0000.5012.0000
Cordset, pre-assembled	
M12 female connector with coupling nut, 2 m [6.56'] PVC cable	05.00.6041.8211.002M
M23 female connector with coupling nut, 2 m [6.56'] PVC cable	8.0000.6901.0002.0031

Further accessories can be found in the accessories section or in the accessories area of our website at: www.kuebler.com/accessories.
 Additional connectors can be found in the connection technology section or in the connection technology area of our website at: www.kuebler.com/connection_technology.

1) Resolution, preset value and counting direction factory-programmable.
 2) Only in conjunction with interface type 1 and 2.
 3) For the cable connection type, cable material PUR.

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Technical data

Mechanical characteristics		
Maximum speed shaft version		
IP65 up to 70°C [158°F]	12000 min ⁻¹ , 10000 min ⁻¹ (continuous)	
IP65 up to T _{max}	8000 min ⁻¹ , 5000 min ⁻¹ (continuous)	
IP67 up to 70°C [158°F]	11000 min ⁻¹ , 9000 min ⁻¹ (continuous)	
IP67 up to T _{max}	8000 min ⁻¹ , 5000 min ⁻¹ (continuous)	
Maximum speed hollow shaft version		
IP65 up to 70°C [158°F]	9000 min ⁻¹ , 6000 min ⁻¹ (continuous)	
IP65 up to T _{max}	6000 min ⁻¹ , 3000 min ⁻¹ (continuous)	
IP67 up to 70°C [158°F]	8000 min ⁻¹ , 4000 min ⁻¹ (continuous)	
IP67 up to T _{max}	4000 min ⁻¹ , 2000 min ⁻¹ (continuous)	
Starting torque at 20°C [68°F]	IP65	< 0.01 Nm
	IP67	< 0.05 Nm
Mass moment of inertia		
	shaft version	4.0 x 10 ⁻⁶ kgm ²
	hollow shaft version	7.0 x 10 ⁻⁶ kgm ²
Load capacity of shaft	radial	80 N
	axial	40 N
Weight		approx. 0.45 kg [15.87 oz]
Protection acc. to EN 60529		
	housing side	IP67
	shaft side	IP65, opt. IP67
Working temperature range		-40°C ... +90°C [-40°F ... +194°F] ¹⁾
Material	shaft/hollow shaft	stainless steel
	flange	aluminium
	housing	zinc die-cast
	able	PVC
Shock resistance acc. to EN 60068-2-27		2500 m/s ² , 6 ms
Vibration resistance acc. to EN 60068-2-6		100 m/s ² , 55 ... 2000 Hz

Electrical characteristics		
Power supply		5 V DC (+5%) or 10 ... 30 V DC
Current consumption (no load)	5 V DC	max. 80 mA
	10 ... 30 V DC	max. 50 mA
Reverse polarity protection of the power supply		yes (at 10 ... 30 V DC)
Short circuit proof outputs		yes ²⁾
UL approval		file 224618
CE compliant acc. to		EMC guideline 2014/30/EU RoHS guideline 2011/65/EU

SSI interface		
Output driver		RS485 transceiver type
Permissible load / channel		max. +/- 20 mA
Signal level	HIGH	typ. 3.8 V
	LOW at I _{Load} = 20 mA	typ. 1.3 V
Resolution singleturn		10 ... 14 bit and 17 bit
Number of revolutions (multiturn)		4096 (12 bit)
Code		binary or gray
SSI clock rate		50 kHz ... 2 MHz
Data refresh rate	ST resolution ≤ 14 bit	≤ 1 μs
	ST resolution ≥ 15 bit	4 μs
Monoflop time		≤ 15 μs
Note: If the clock starts cycling within the monoflop time, a second data transfer starts with the same data. If the clock starts cycling after the monoflop time, the data transfer starts with the new values. The update rate is dependent on the clock speed, data length and monoflop-time.		

BiSS interface	
Resolution singleturn	10 ... 14 bit and 17 bit
Number of revolutions (multiturn)	4096 (12 bit)
Code	binary
Clock rate	50 kHz ... 10 MHz
Max. update rate	< 10 μs, depends on the clock rate and the data length
Data refresh rate	≤ 1 μs
Note:	<ul style="list-style-type: none"> – bidirectional, factory programmable parameters are: resolution, code, direction, alarms and warnings – CRC data verification

Status output and LED	
Output driver	open collector, internal pull up resistor 22 kOhm
Permissible load	max. 20 mA
Signal level	HIGH: +V / LOW: < 1 V
Active	LOW
The optional LED (red) and the status output serve to display various alarm or error messages. In normal operation the LED is OFF and the status output is HIGH (open collector with int. pull up 22 kOhm).	
An active status output (LOW) displays: <ul style="list-style-type: none"> – sensor error, singleturn or multiturn (soiling, glass breakage etc.) – LED fault (failure or ageing) – over- or under-temperature 	
In the SSI mode, the fault indication can only be reset by switching off the power-supply to the device.	

Option incremental outputs (A/B), 2048 ppr		
	SinCos	RS422 TTL compatible
Max. frequency -3dB	400 kHz	400 kHz
Signal level	1 V _{pp} (± 20%)	HIGH: min. 2.5 V LOW: max. 0.5 V
Short circuit proof	yes	yes

1) Cable version: -30°C ... +75°C [-22°F ... +167°F].
2) Short circuit to 0V or to output, one channel at a time, power supply correctly applied.

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SET input or SET button			
Input	active HIGH		
Input type	comparator		
Signal level	HIGH	min: 60 % of +V (power supply) max: +V	
	LOW	max: 25 % of +V (power supply)	
Input current	< 0.5 mA		
Min. pulse duration (SET)	10 ms		
Timeout after SET signal	14 ms		
Response time (DIR input)	1 ms		
<p>The encoder can be set to zero at any position by means of a HIGH signal on the SET input or by pressing the optional SET button (with a pencil, ball-point pen or similar). Other preset values can be factory-programmed. The SET input has a signal processing time of approx. 1 ms. Once the SET function has been triggered, the encoder requires an internal processing time of approx. 15 ms before the new position data can be read. During this time the status output is at LOW.</p> <p>If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.</p>			
DIR input			
<p>Direction input: A HIGH signal switches the direction of rotation from the default cw to ccw. This inverted function can also be factory-programmed.</p> <p>If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.</p>			
Power-ON Time			
<p>After Power-ON the device requires a time of approx. 150 ms before valid data can be read.</p> <p>Hot plugging of the encoder should be avoided.</p>			

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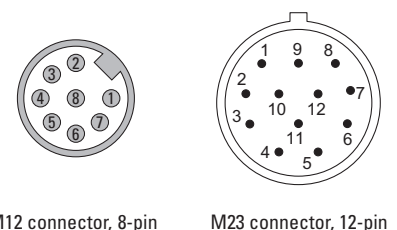
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Terminal assignment

Interface	Type of connection	Features	Cable (isolate unused wires individually before initial start-up)
1, 2	1, 2, A, B, E, F	SET, DIR, Status	Signal: 0 V +V C+ C- D+ D- SET DIR Stat N/C N/C N/C \perp
			Cable colour: WH BN GN YE GY PK BU RD BK - - - shield
1, 2	3, 4	SET, DIR, Status	M23 connector
			Signal: 0 V +V C+ C- D+ D- SET DIR Stat N/C N/C N/C \perp
1, 2	3, 4	SET, DIR, Status	Pin: 1 2 3 4 5 6 7 8 9 10 11 12 PH
			5
Signal: 0 V +V C+ C- D+ D- SET DIR Stat N/C 0Vsens +Vsens \perp			
5	1, 2, A, B, E, F	SET, DIR, Status sensor output	Cable colour: WH BN GN YE GY PK BU RD BK - GY-PK RD-BU shield
			5
Signal: 0 V +V C+ C- D+ D- SET DIR Stat N/C 0Vsens +Vsens \perp			
5	3, 4	SET, DIR, Status sensor output	Pin: 1 2 3 4 5 6 7 8 9 10 11 12 PH
			3, 4, 7, 8
Signal: 0 V +V C+ C- D+ D- SET DIR A \bar{A} B \bar{B} \perp			
3, 4, 7, 8	1, 2, A, B, E, F	SET, DIR, SinCos or incr. RS422	Cable colour: WH BN GN YE GY PK BU RD BK VT GY-PK RD-BU shield
			3, 4, 7, 8
Signal: 0 V +V C+ C- D+ D- SET DIR A \bar{A} B \bar{B} \perp			
3, 4, 7, 8	3, 4	SET, DIR, SinCos or incr. RS422	Pin: 1 2 3 4 5 6 7 8 9 10 11 12 PH
			6, 9
Signal: 0 V +V C+ C- D+ D- A \bar{A} B \bar{B} 0Vsens +Vsens \perp			
6, 9	1, 2, A, B, E, F	SinCos o. incr. RS422 sensor output	Cable colour: WH BN GN YE GY PK BU RD BK VT GY-PK RD-BU shield
			6, 9
Signal: 0 V +V C+ C- D+ D- A \bar{A} B \bar{B} 0Vsens +Vsens \perp			
6, 9	3, 4	SinCos o. incr. RS422 sensor output	Pin: 1 2 3 4 5 6 7 8 9 10 11 12 PH
			1, 2
Signal: 0 V +V C+ C- D+ D- SET DIR \perp			
1, 2	5, 6	SET, DIR	Pin: 1 2 3 4 5 6 7 8 PH

- +V: Encoder power supply +V DC
- 0 V: Encoder power supply ground GND (0 V)
- 0 Vsens / +Vsens: Using the sensor outputs of the encoder, the voltage present can be measured and if necessary increased accordingly.
- C+, C-: Clock signal
- D+, D-: Data signal
- A, \bar{A} : Incremental output channel A (cosine)
- B, \bar{B} : Incremental output channel B (sine)
- SET: SET input
- DIR: Direction input
- Stat: Status output
- PH \perp : Plug connector housing (shield)

Top view of mating side, male contact base



M12 connector, 8-pin

M23 connector, 12-pin

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Dimensions shaft version

Dimensions in mm [inch]

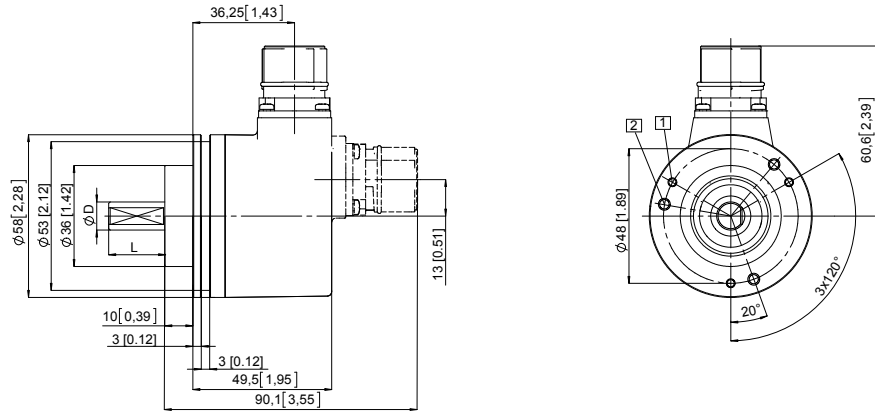
Clamping flange, \varnothing 58 [2.28]

Flange type 1 and 3

(drawing with M23 connector)

- 1 3 x M3, 6 [0.24] deep
- 2 3 x M4, 8 [0.32] deep

D	L	Fit
6 [0.24]	10 [0.39]	h7
10 [0.39]	20 [0.79]	f7
1/4"	7/8"	h7
3/8"	7/8"	h7



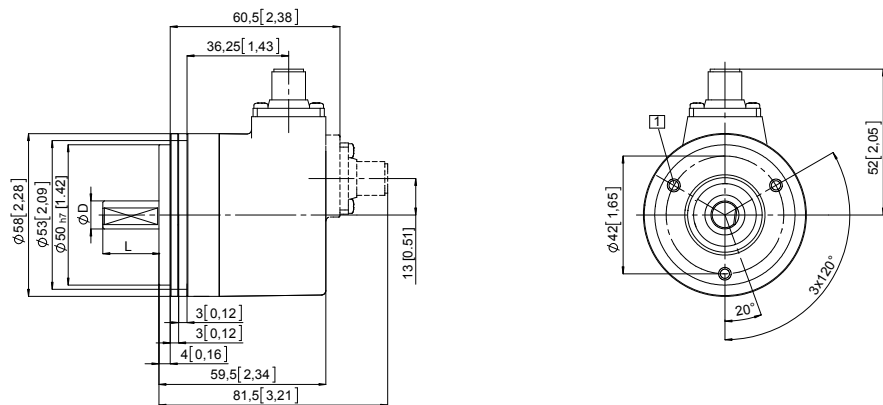
Synchro flange, \varnothing 58 [2.28]

Flange type 2 and 4

(drawing with M12 connector)

- 1 M4, 6 [0.24] deep

D	L	Fit
6 [0.24]	10 [0.39]	h7
10 [0.39]	20 [0.79]	f7
1/4"	7/8"	h7
3/8"	7/8"	h7

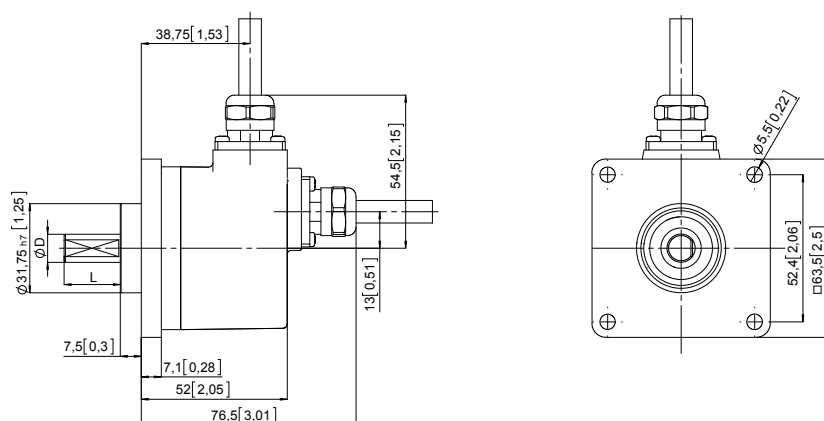


Square flange, \square 63.5 [2.5]

Flange type 5 and 7

(drawing with cable)

D	L	Fit
6 [0.24]	10 [0.39]	h7
10 [0.39]	20 [0.79]	f7
1/4"	7/8"	h7
3/8"	7/8"	h7



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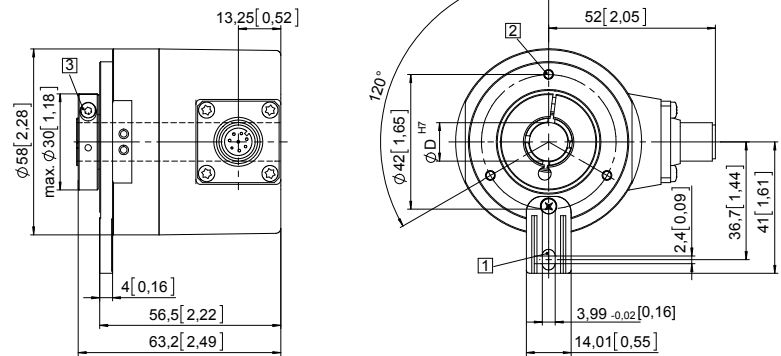
Dimensions hollow shaft version

Dimensions in mm [inch]

Flange with spring element, long Flange type 1 and 2

(drawing with M12 connector)

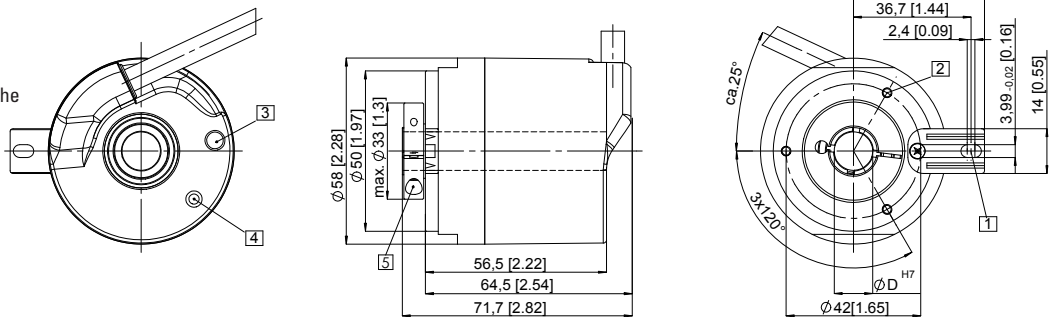
- 1 Torque stop slot, recommendation: cylindrical pin DIN 7, \varnothing 4 [0.16]
- 2 M3, 6 [0.24] deep
- 3 Recommended torque for the clamping ring 0.6 Nm



Flange with spring element, long Flange type 1 and 2

(drawing with tangential cable)

- 1 Torque stop slot, recommendation: cylindrical pin DIN 7, \varnothing 4 [0.16]
- 2 M3, 5.5 [0.21] deep
- 3 Status-LED
- 4 SET button
- 5 Recommended torque for the clamping ring 0.6 Nm



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SSI / BiSS

Dimensions hollow shaft version

Dimensions in mm [inch]

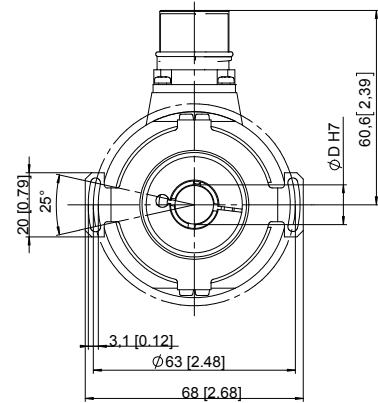
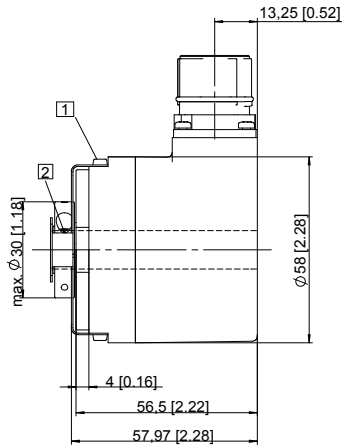
Flange with stator coupling, \varnothing 63 [2.48]

Flange type 5 and 6

Pitch circle diameter for fixing screws 63 [2.48]

(drawing with M23 connector)

- 1 Fixing screws DIN 912 M3 x 8
(washer included in delivery)
- 2 Recommended torque for the
clamping ring 0.6 Nm



Flange with stator coupling, \varnothing 65 [2.56]

Flange type 3 and 4

Pitch circle diameter for fixing screws 65 [2.56]

(drawing with cable)

- 1 Recommended torque for the
clamping ring 0.6 Nm

