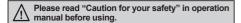
Compact, amplifier built-in type with Universal voltage

Features

- Small and power supply built-in type
- Easy installation with LED indicators on product
- Enables to set the operation mode by VR (Light ON/Dark ON)
- Status and output LED indication
- Built-in IC photo diode for ambient light and electrical noise







Specifications

• Free power, Relay contact output type

Model		BEN10M-TFR	BEN5M-MFR	BEN3M-PFR	BEN300-DFR	
Sensing	type	Through-beam	Retroreflective (Standard type)	Retroreflective (Built-in polarizing filter)	Diffuse reflective	
Sensing distance		10m	0.1 to 5m ^{×1}	0.1 to 3m ^{×1}	300mm ^{*2}	
Sensing target		Opaque materials of Min. Ø16mm	Opaque materials of Min. Ø60mm		Translucent, Opaque materials	
Hysteresis		_		Max. 20% at ratedsetting distance		
Response time		Max. 20ms				
Power su	ipply	24-240VAC ±10% 50/60Hz, 24-240VDC ±10%(Ripple P-P: Max. 10%)				
Current of	consumption	Max. 4VA				
Light sou	rce	Infrared LED(850nm)		Red LED(660nm)	Infrared LED(940nm)	
Sensitivit	y adjustment	_	Adjustment VR			
Operation mode		Selectable Light ON or Dark ON by VR				
Control output		Relay contact output Relay contact capacity: 30VDC 3A of resistive load, 250VAC 3A resistive load Relay contact composition: 1c				
Relay life cycle		Mechanically: Min. 50,000,000 operation, Electrically: Min. 100,000 operation				
Light receiving element		Photo IC				
Indicator		Operation indicator: red, Stability indicator: green (The red lamp on Emitter of transmitted beam type is for power indication)				
Insulation resistance		Min. 20MΩ(at 500VDC megger)				
Insulation	n type	Double or strong insulation(Mark: , Dielectric voltage between the measured input and the power: 1kV)				
Noise res	sistance	±1,000V the square wave noise(pulse width: 1μs) by the noise simulator				
Dielectric	strength	1000VAC 50/60Hz for 1minute				
Vibration	Mechanical	1.5mm amplitude at frequency of 10 to 55Hz(for 1 min.) in each of X, Y, Z directions for 2 hours				
Vibration	Malfunction	1.5mm amplitude at frequency of 10 to 55Hz(for 1 min.) in each of X, Y, Z directions for 10 minutes				
Shock	Mechanical	500m/s²(approx. 50G) in each of X, Y, Z directions for 3 times				
SHOCK	Malfunction	100m/s²(approx. 10G) in each of X, Y, Z directions for 3 times				
	Ambient illumination	Sunlight: Max. 11,0001x, Incandescent lamp: Max. 3,0001x (Receiver illumination)				
Environ- ment	Ambient temperature	-20 to 65°C, storage: -25 to 70°C				
Inche	Ambient humidity	35 to 85%RH, storage: 35 to 85%RH				
Protection		IP50(IEC standard)				
Material		Case, Case cover: Heat resistant ABS Sensing part: PC(with polarizing filter: PMMA)				
Cable		Ø5mm, 5-wire, Length: 2m(Emitter of through-beam type: Ø5mm, 2-wire, Length: 2m) (AWG22, Core diameter: 0.08mm, Number of cores: 60, Insulator out diameter: Ø1.25mm)				
A 00000	Individual	_	Reflector(MS-2)			
Accessory	Common	VR adjustment driver, Mounting bracket, Bolts/nuts				
Unit weight		Approx. 354g	Approx. 208g		Approx. 195g	
※1 ⋅ The	sensing distance is s	specified with using the MS-	2 reflector and same as the	MS-4 reflector Sensing dist	tance is setting range of the	

^{**1:} The sensing distance is specified with using the MS-2 reflector and same as the MS-4 reflector. Sensing distance is setting range of the reflector. The sensor can detect under 0.1m.

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When using reflective tapes, the reflection efficiency will vary by the size of the tape. Please refer to the "Reflection efficiency by reflective tape model" table before using the tapes.

 $[\]times$ 2: It is for Non-glossy white paper(100×100mm).

^{*}The temperature or humidity mentioned in Environment indicates a non freezing or condensation environment.

Amplifier Built-in type with Universal voltage

• DC power, Solid state output type

Model		BEN10M-TDT	BEN5M-MDT	BEN3M-PDT	BEN300-DDT	Photo electric sensor	
Sensing t	type	Through-beam	Retroreflective	Retroreflective (with polarizing filter)	Diffuse reflective	(B) Fiber	
Sensing of	distance	10m	0.1 to 5m *1	0.1 to 3m *1	300mm **2	optic sensor	
Sensing target		Opaque materials of Min. Ø16mm	Opaque materials of	Opaque materials of Min. Ø60mm		(C) Door/Area	
Hysteresis		_			Max. 20% at rated setting distance	sensor	
Response	e time	Max. 1ms				(D) Proximity	
Power supply		12-24VDC ±10%(Ripple P-P: Max. 10%)				sensor	
Current c	onsumption	Max. 50mA				(E)	
Light source		Infrared LED(850nm)		Red LED(660nm)	Infrared LED(940nm)	Pressure sensor	
Sensitivity	y adjustment	_	Adjustment VR			3611301	
Operation	n mode	Selectable Light ON or D	ark ON by VR			(F)	
Control o	utput	NPN open collector / PNP open collector simultaneous output ◆Load voltage: Max. 30VDC ◆Load current: Max. 200mA ◆Residual voltage - NPN: Max. 1V, PNP: Max. 2.5V				Rotary encoder	
Protection	n circuit	Reverse polarity protection	Reverse polarity protection, Short-circuit protection				
Light receiving element		Photo IC				Connector/ Socket	
Indicator		Operation indicator: Red, Stability indicator: Green (The red lamp on Emitter of transmitted beam type is for power indication)				(H)	
Insulation resistance		Min. 20MΩ(at 500VDC megger)				Temp. controller	
Noise res	sistance	±240V the square wave	noise(pulse width: 1µs) b	by the noise simulator		m	
Dielectric	strength	1000VAC 50/60Hz for 1minute				(I) SSR/	
Vibration		1.5mm amplitude at frequency of 10 to 55Hz(for 1 min.) in each of X, Y, Z directions for 2 hours				Power controller	
Shock		500m/s²(approx. 50G) in each of X, Y, Z directions for 3 times					
	Ambient illumination	Sunlight: Max. 11,0001x Incandescent lamp: Max. 3,0001x (Receiver illumination)			(J) Counter		
Environ- ment	Ambient temperature	e -20 to 65°C, storage: -25 to 70°C					
IIICIII	Ambient humidity	35 to 85%RH, storage: 35 to 85%RH			(K)		
Protection	n	IP50(IEC standard)				Timer	
Material		• Case, Case cover: Heat resistant ABS • Sensing part: PC(with polarizing filter: PMMA)					
Cable		Ø5mm, 4-wire, Length: 2m(Emitter of through-beam type: Ø5mm, 2-wire, Length: 2m) (AWG22, Core diameter: 0.08mm, Number of cores: 60, Insulator diameter: Ø1.25mm)				(L) Panel meter	
A 0000005	Individual	_	Reflector(MS-2)		_		
Accessory		VR adjustment driver, Mounting bracket, Bolts/nuts				(M) Tacho/ Speed/ Pul	
Approval		C € Approx. 342q	Approx. 200g		Approx. 187g	meter	
Unit weight X1: The sensing distance is			LAnnroy 200a				

^{*1:} The sensing distance is specified with using the MS-2 reflector and same as the MS-4 reflector. Sensing distance is setting range of the reflector. The sensor can detect under 0.1m.

When using reflective tapes, the reflection efficiency will vary by the size of the tape. Please refer to the "Reflection efficiency by reflective tape model" table before using the tapes.

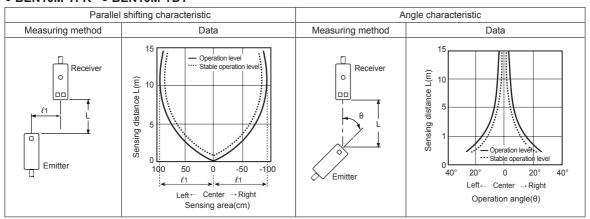
X2: It is for Non-glossy white paper(100×100mm)

*The temperature or humidity mentioned in Environment indicates a non freezing or condensation environment.

Feature data

Through-beam type

• BEN10M-TFR • BEN10M-TDT



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(O) Sensor controller

(P) Switching

mode powe supply

motor& Driver&Co

(R) Graphic/ Logic panel

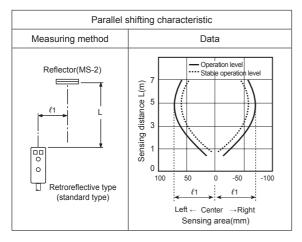
(S) Field network device

BEN Series

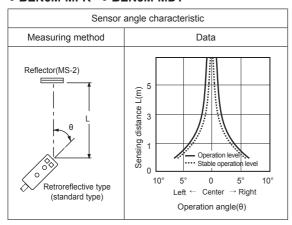
Feature data

Retroreflective type(Standard type)

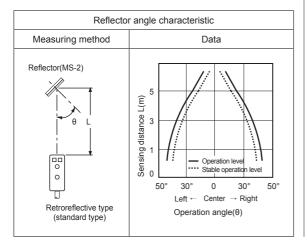
• BEN5M-MFR • BEN5M-MDT



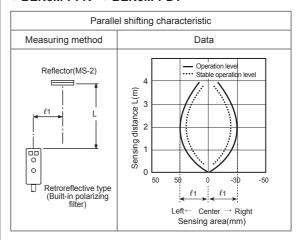
BEN5M-MFR BEN5M-MDT



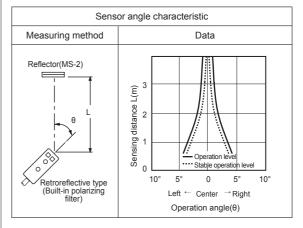
• BEN5M-MFR • BEN5M-MDT



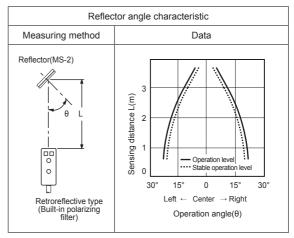
• BEN3M-PFR • BEN3M-PDT



BEN3M-PFR BEN3M-PDT



• BEN3M-PFR • BEN3M-PDT

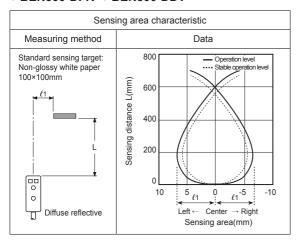


A-46 Autonics

Amplifier Built-in type with Universal voltage

O Diffuse reflective type

• BEN300-DFR • BEN300-DDT



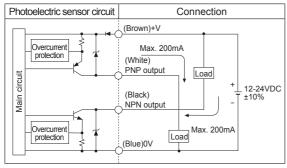
Operation mode

Operation mode	Light ON		
Receiver operation	Received light		
r tooorror operation	Interrupted light		
Operation indicator	ON		
(red LED)	OFF		
Transiator autaut	ON		
Transistor output	OFF		

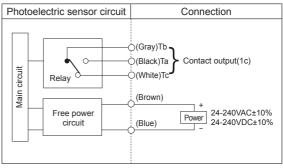
Operation mode	Dark ON		
Receiver operation	Received light Interrupted light		
Operation indicator (red LED)	ON OFF		
Transistor output	ON OFF		

■ Control output diagram

• DC voltage(NPN/PNP synchronous output)

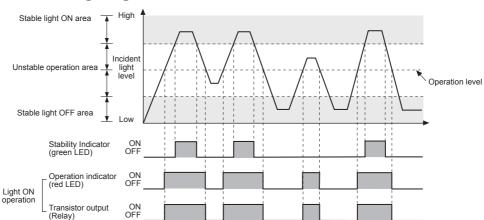


Free power(Relay contact output)



*In case of product with the output protection device, if terminals of control output are short circuited or overcurrent condition exists, the control output turns OFF due to protection circuit.

Operation timing diagram



**The waveforms of "Operation indicator" and "Transistor output" are for Light ON operation.
They are opposite operation for Dark ON operation.

Autonics A-47

(A) Photo electric sensor

> (B) Fiber optic sensor

(C) Door/Area sensor (D) Proximity

(E) Pressure sensor

(F) Rotary encoder

(G) Connector/ Socket

(H) Temp. controller

(I) SSR/ Power controller

(J) Counter

(K) Timer

Panel meter

(M) Tacho/ Speed/ Pulse meter

(N) Display unit (O) Sensor controller

(P) Switching mode power supply

(Q) Stepper

motor& Driver&Controlle (R) Graphic/ Logic panel

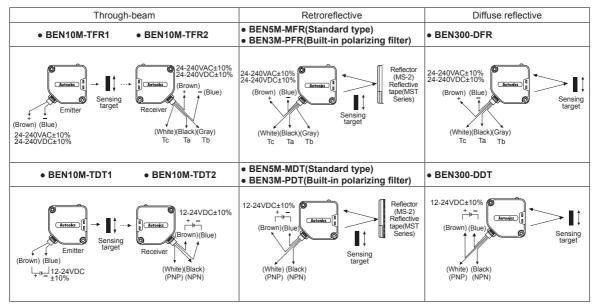
(S) Field network device

(T) Software

(U) Othe

BEN Series

Connections



* Unused line must be insulated.

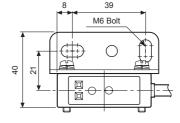
Dimensions

(unit: mm)

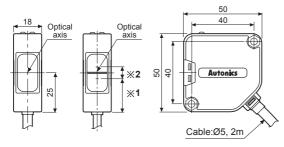
Operation mode selection VR Stability indicator Operation mode selection VR Adjustment VR

(Except for through-beam type)

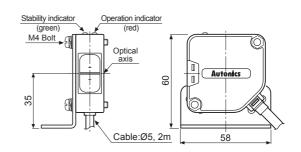
• Connect the bracket



•Through-beam •Retroreflective •Diffuse reflective



X1: Retroreflective: 21.25mm, Diffuse reflective: 20.25mmX2: Retroreflective: 7.5mm, Diffuse reflective: 9.5mm



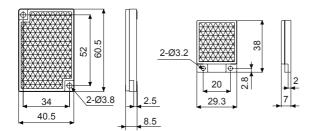
A-48 Autonics

Amplifier Built-in type with Universal voltage

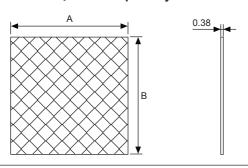
Reflector

· MS-2

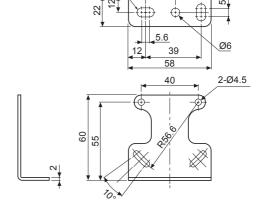
· MS-4(sold separately)



Reflective tape(sold separately)



Bracket



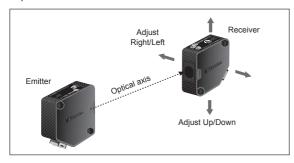
M6 Bolt

	А	В
MST-50-10	50	50
MST-100-5	100	100
MST-200-2	200	200

■ Mounting and sensitivity adjustment

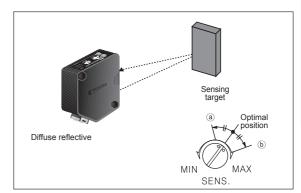
Through-beam type

- Supply the power to the photoelectric sensor, after setting the emitter and the receiver facing each other.
- Set the receiver in center of position in the middle of the stability range of indicator adjusting the receiver or the emitter right and left, up and down.
- 3. After adjustment, check the stability of operation putting the object at the optical axis.
- XIf the sensing target is translucent body or smaller than Ø16mm, it can be missed by sensor cause light penetrate it.



O Diffuse reflective type

- The sensitivity should be adjusted depending on a sensing target or mounting place.
- Set the target at a position to be detected by the beam, then turn the adjustment VR until position (a) where the operation indicator turns ON from min. position of the adjustment VR.
- 4. Set the adjustment VR at the center of two switching position (a), (b).
- %The sensing distance indicated on specification chart is for 100×100mm of non-glossy white paper. Be sure that it can be different by size, surface and gloss of target.



(A) Photo electric sensor

(B) Fiber optic sensor

(C) Door/Area sensor (D) Proximity

(E)

(E) Pressure sensor

(F) Rotary encoder

Connector/ Socket

(H) Temp. controller

(I) SSR/ Power controller

Counter

(K)

L) Panel neter

(M) Tacho/ Speed/ Pulse meter

(N) Display unit

>)) ensor ontroller

(P) Switching mode power supply

(Q) Stepper motor& Driver&Controller

(R) Graphic/ Logic panel

(S) Field network device

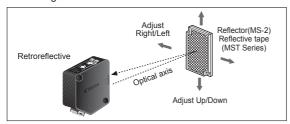
(T) Software

(U) Other

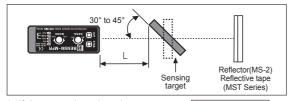
Autonics A-49

Retroreflective type

- Supply the power to the photoelectric sensor, after setting the photoelectric sensor and the reflector or reflective tape in face to face.
- Set the photoelectric sensor in the position which indicator turns on, as adjusting the reflector or the sensor right and left, up and down.
- 3. Fix both units tightly after checking that the unit detects the target.



- If using more than 2 photoelectric sensors in parallel, the space between them should be more than 30cm.
- If reflectance of target is higher than non-glossy white paper, it might cause malfunction by reflection from the target when the target is near to photoelectric sensor. Therefore put enough space between the target and the photoelectric sensor or the surface of the target should be installed at angle of 30° to 45° against optical axis. (When a sensing target with high reflectance near by, photoelectric sensing with the polarizing filter should be used.)
- X Sensitivity adjustment: Refer to the diffuse reflective type's.

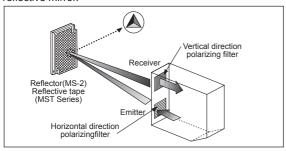


- XIf the mounting place is too narrow, please use MS-4 instead of MS-2.



Retroreflective type with polarizing filter

The light passed through the polarizing filter of the emitter reaches to the MS-2 reflector or reflective tape converting as horizontal direction. It reaches to the receiver element of polarizing filter converting as vertical by the MS-2 reflector or reflective tape. Therefore, this type can also detect reflective mirror.



Reflective efficiency by reflective tape model

	Retroreflective type (Standard)	Retroreflective type (Built-in polarizing filter)
MST-50-10 (50×50mm)	110%	110%
MST-100-5 (100×100mm)	160%	130%
MST-200-2 (200×200mm)	180%	180%

※Reflective efficiency may vary depending on usage environment and installation conditions.

The sensing distance and minimum sensing target size increase as the size of the tape increases.

Please check the reflection efficiency before using reflective tapes.

※For using reflective tape, installation distance should be min. 20mm.

A-50 Autonics