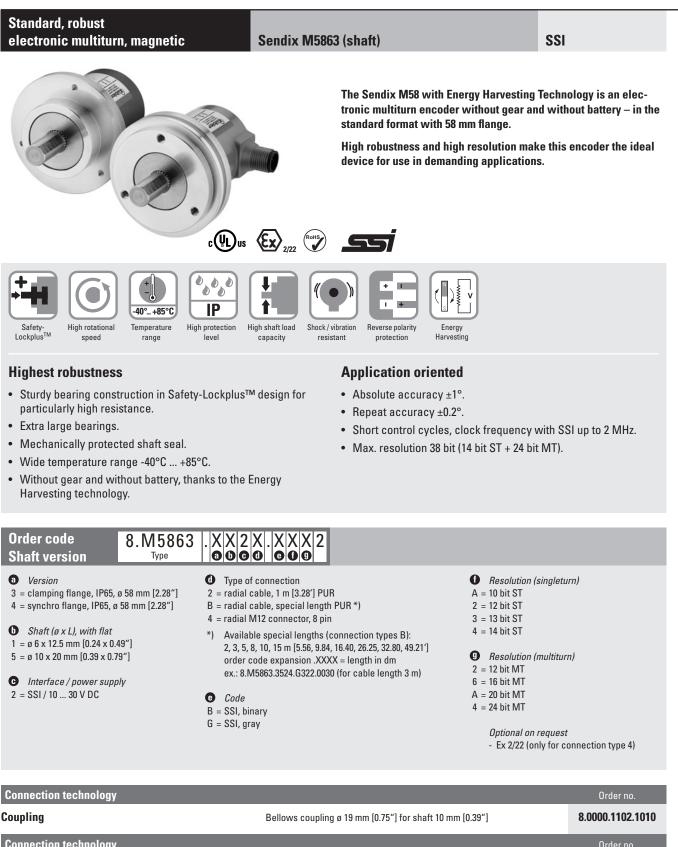
## Absolute encoders – multiturn





| connection technology               |   | Urder no.            |
|-------------------------------------|---|----------------------|
| Connector, self-assembly (straight) | M12 female connector with coupling nut                        | 05.CMB 8181-0        |
| Cordset, pre-assembled              | M12 female connector with coupling nut, 2 m [6.56′] PUR cable | 05.00.6051.8211.002M |

Further accessories can be found in the accessories section or in the accessories area of our website at: www.kuebler.com/accessories. Additional connectors can be found in the connection technology section or in the connection technology area of our website at: www.kuebler.com/connection\_technology.

## Standard, robust

## electronic multiturn, magnetic

## Sendix M5863 (shaft)

SSI

übler

Technical data

#### Mechanical characteristics

| Maximum speed                                 | 4000 min <sup>-1</sup><br>2000 min <sup>-1</sup> (continuous) |
|---|---|
| Starting torque at 20°C [68°F]                | < 0.01 Nm   |
| Shaft load capacity radial axial              | 80 N<br>40 N  |
| Weight  | approx. 0.2 kg [7.06 oz]                                      |
| Protection acc. to EN 60529/DIN 40050-9       | IP65  |
| Working temperature range                     | -40°C +85°C [-40°F +185°F]                                    |
| Materials shaft<br>flange<br>housing<br>cable | V2A<br>aluminium<br>zinc die-cast<br>PUR                      |
| Shock resistance acc. to EN 60068-2-27        | 5000 m/s², 4 ms   |
| Vibration resistance acc. to EN 60068-2-6     | 300 m/s <sup>2</sup> , 10 2000 Hz                             |

## Electrical characteristics

| Power supply                                       | 10 30 V DC  |
|--|---|
| Current consumption (no load)                      | max. 30 mA  |
| Reverse polarity protection of the<br>power supply | yes   |
| Short-circuit proof outputs                        | yes 1)  |
| UL approval  | File 224618   |
| <b>CE compliant</b> acc. to                        | EMC guideline 2014/30/EU<br>RoHS guideline 2011/65/EU |

## SSI interface

| Output driver                       | RS485 transceiver type |  |  |
|-------------------------------------|------------------------|--|--|
| Permissible load / channel          | max. +/- 30 mA         |  |  |
| Signal level HIGH                   | typ 3.8 V              |  |  |
| LOW with $I_{Load} = 20 \text{ mA}$ | typ 1.3 V              |  |  |
| Resolution singleturn               | 10 14 bit              |  |  |
| Absoulte accuracy <sup>2)</sup>     | ±1°                    |  |  |
| Repeat accuracy                     | ±0.2°                  |  |  |
| Number of revolutions (multiturn)   | max. 24 bit            |  |  |
| Code                                | binary or gray         |  |  |
| SSI clock rate                      | 50 kHz 2 MHz           |  |  |
| Data refresh rate                   | 2 ms                   |  |  |
| Monoflop time                       | ≤ 15 µs                |  |  |

**Note:** If the clock cycle starts within the monoflop time a second data transfer begins with the same data. If the clock cycle starts after the monoflop time the cycle begins with the new values. The update rate is dependent on the clock speed, data length and monoflop time.

| SET input                        |      |                          |
|----------------------------------|------|--------------------------|
| Input                            |      | active HIGH              |
| Input type                       |      | comparator               |
| Signal level                     | HIGH | min. 60 % of +V, max: +V |
| (+V = power supply)              | LOW  | max. 30 % of +V          |
| Input current                    |      | < 0.5 mA                 |
| Min. pulse duration (SET)        |      | 10 ms                    |
| Input delay                      |      | 1 ms                     |
| New position data readable after | r    | 1 ms                     |
| Internal processing time         |      | 200 ms                   |
|                                  |      |                          |

The encoder can be set to zero at any position by means of a HIGH signal on the SET input. Other preset values can be factory-programmed. The SET input has a signal processing time of approx. 1 ms, after which the new position data can be read via SSI or BiSS. Once the SET function has been triggered, the encoder requires an internal processing time of typ. 200 ms; during this time the power supply must not be switched off.

The SET function should be carried out whilst the encoder is at rest.

If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.

### **DIR** input

Direction input: A HIGH signal switches the direction of rotation from the default cw to ccw. This inverted function can also be factory-programmed.

1 ms

If this input is not used, it should be connected to 0 V (Encoder ground GND) in order to avoid interferences.

Response time (DIR input)

## Power-ON Time

After Power-ON the device requires a time of approx. 150  $\rm ms$  before valid data can be read.

Hot plugging of the encoder should be avoided.

1) Short circuit proof to 0 V or to output when power supply correctly applied.

2) Over the whole temperature range.

# Absolute encoders – multiturn

| Standard, robust               |                      |     |
|--------------------------------|----------------------|-----|
| electronic multiturn, magnetic | Sendix M5863 (shaft) | SSI |

#### **Terminal assignment**

| Interface       | Type of connection | Features | Cable (isolate unused wires individually before initial start-up) |    |    |    |    |     |     |    |    |        |
|-----------------|--------------------|----------|---|----|----|----|----|-----|-----|----|----|--------|
| 2 2, B SET, DIR | Signal:            | 0 V      | +V  | C+ | C- | D+ | D- | SET | DIR | Ŧ  |    |        |
| 2               | 2, B               | SEI, DIN | Cable colour:   | WH | BN | GN | YE | GY  | PK  | BU | RD | shield |
|                 |                    |          |   |    |    |    |    |     |     |    |    |        |
| Interface       | Type of connection | Features | M12 connector, 8-pin  |    |    |    |    |     |     |    |    |        |
|                 | Signal:            | 0 V      | +V  | C+ | C- | D+ | D- | SET | DIR | Ŧ  |    |        |
| 2               | 4 SET, DIR         |          | Pin:  | 1  | 2  | 3  | 4  | 5   | 6   | 7  | 8  | РН     |

| +V:     | Encoder power supply +V DC            |
|---------|---------------------------------------|
| 0 V:    | Encoder power supply ground GND (0 V) |
| C+, C-: | Clock signal                          |
| D+, D-: | Data signal                           |
| SET:    | Set input                             |
| DIR:    | Direction input                       |
| PH ≟:   | Plug connector housing (shield)       |

#### Top view of mating side, male contact base



M12 connector, 8-pin

### Dimensions

Dimensions in mm [inch]

#### Clamping flange, ø 58 [2.28] Flange type 3

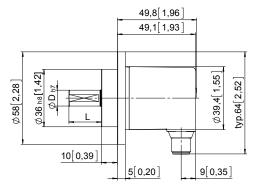
1 3 x M3, 6 [0.24] deep

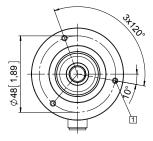
| D         | L           | Fit |
|-----------|-------------|-----|
| 6 [0.24]  | 12,5 [0.49] | h7  |
| 10 [0.39] | 20 [0.79]   | h7  |

## Synchro flange, ø 58 [2.28] Flange type 4

1 3 x M4, 10 [0.39] deep

| D         | L           | Fit |
|-----------|-------------|-----|
| 6 [0.24]  | 12,5 [0.49] | h7  |
| 10 [0.39] | 20 [0.79]   | h7  |





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