Date: 2006.05.18

# DISTANCE MEASURING TYPE Obstacle Detection Sensor UBG-05LN

Specifications

Symbol	Amended Reason				Page	Date	Corrector	
Approved	Checked	Drawn	Designed	Title	Obstacle Detection Sensor			sor
				litte	UBG-05LN Specifications			
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#### 1. Outline

## 1. Operating Principle

UBG-05LN is an obstacle detection sensor with 785nm wavelength laser light source. It detect objects in the predefined area by scanning 180° semicircle and calculates the coordinates of the detected object by measuring its distance and angle. The product is laser class 1 safe.

### 2. Area Setting

31 different area patterns and their coordinate points can be set using application software and serial communication RS232C.

3-step outputs can be selected for each area.

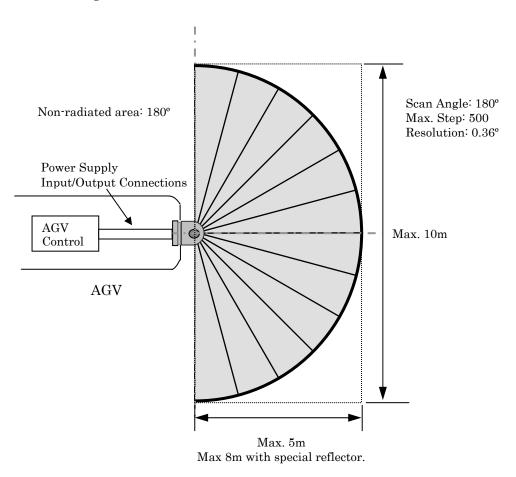
## 3. Area Switching

Bit input at terminal points switches the predefined area patterns.

## 4. Malfunction Output

Self-diagnostic functions continuously check laser radiation and motor rotation and supplies malfunction output upon error detection.

# 2. Structure (Scan Image)



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# 3. Specifications

Model	UBG-05LN
Light source	Semiconductor laser diode (λ=785nm)
	Laser safety Class 1 (FDA)
	Laser power:0.8mW or less(Scanning satishfies the laser Class 1
	safety.)
Power source	24V DC ±10% (Startup voltage range 18~30V)
Current consumption	150mA or less (Rush current 300mA)
Detection distance	$100$ mm ~ $5000$ mm* (White sheet $125 \times 125$ mm or more)
	100mm ~ 8000mm* (Specific reflector 250×250 mm or more)
Accuracy	Distance 100 ~ 1000mm: ±20mm*
	Distance $1000 \sim 4000$ mm: $\pm 2\%$ of measurement*
	Repeatability ±10mm*
Hyteresis	Values specified while setting area patterns (Default: 6.25%)
	6.25% of detection distance (not less than 60 mm)
	3.17% of detection distance (not less than 30 mm)
Outputs	Photo coupler open collector output (DC 30V, 50mA max.)
	Output 1: Turns OFF during object detection inside area.
	Output 2: Turns OFF during object detection inside area.
	Output 3: Turns OFF during object detection inside area.
	Malfunction Output: Always ON during normal operation.
G A 1	(Note: All the outputs turn OFF during malfunction)
Scan Angle	$180^{\circ}$ (Resolution $0.36^{\circ}$ )
Scan Time	100msec/scan
Output	Less than 210 msec
Response Time	(Note: Additional delay of max. 100 msec (1 scan time) will occur
Ctant van Time	during area switching)  Within 10 and from payon supply (Varies with startum and itians)
Start up Time	Within 10 sec after power supply. (Varies with startup conditions)  Power supply (Green): Flashes during startup or sensor malfunction
Light Display	Output 1 (Orange): Switches on during object detection inside area
	Output 2 (Orange): Switches on during object detection inside area.
	Output 3 (Orange): Switches on during object detection inside area.
Connection	Flying lead cable (1m)
Ambient Light	Halogen/Mercury light: 10000Lx or less
Resistance	Fluorescent Light: 6000 Lx (max.)
TVCSIS BATTOC	(Note: Direct sunlight or strong light source may cause misdetections)
Ambient Conditions	(
Temperature:	-10 ~ 50°C
Humidity:	85% or less (non-condensing)
Storage temperature	-25 ~ 75°C
Vibration Resistance	Double amplitude 1.5mm 10 ~ 55Hz, 2 hours XYZ direction, and
	$98\text{m/s}^2$ $55\text{Hz} \sim 200\text{Hz}$ in 2 minutes sweep, 1 hours in XYZ directions
Impact Resistance	196 m/s <sup>2</sup> (10G), 10 times in XYZ directions
Weight	Approx. 185g (260g with cable)
Protection Class	IP64
Case	Front: Polycarbonate / Back: ABS
External dimension	60 W×60 H×75 D mm
External dimension	60 W×60 H×75 D mm

<sup>\*</sup>Under standard test conditions.

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Area Setting	Output1 setting: Area with maximum 7 points form 0 to 5000mm							
C	Output2 setting: Straight							
	: Fan Shape							
	: Percentage of Output1 area points							
	Output3 setting: Same as Output2							
Inputs and Area	Photo coupler input (Anode common, supply current to switch on							
Selection	inputs = 4mA)							
	Area Switching: Set area numbers with [Input1][Input2] [Input3][Input4][Input5] Laser radiation stops with all inputs ON. High: OFF Low: ON							
	_	1	f= -1	[ f=	f=	T		
	[Input1]	[Input2]	[Input3]	[Input4]	[Input5]	Area Patterns		
	ON OFF	ON ON	ON ON	ON ON	ON ON	Laser OFF Area 1		
	ON	OFF	ON	ON	ON	Area 2		
	OFF	OFF	ON	ON	ON	Area 3		
	ON	ON	OFF	ON	ON	Area 4		
	OFF	ON	OFF	ON	ON	Area 5		
	ON	OFF	OFF	ON	ON	Area 6		
	OFF	OFF	OFF	ON	ON	Area 7		
	ON	ON	ON	OFF	ON	Area 8		
	OFF	ON	ON	OFF	ON	Area 9		
	ON	OFF	ON	OFF	ON	Area 10		
	OFF	OFF	ON	OFF	ON	Area 11		
	ON OFF	ON ON	OFF OFF	OFF OFF	ON ON	Area 12 Area 13		
	ON	OFF	OFF	OFF	ON	Area 13		
	OFF	OFF	OFF	OFF	ON	Area 15		
	ON	ON	ON	ON	OFF	Area 16		
	OFF	ON	ON	ON	OFF	Area 17		
	ON	OFF	ON	ON	OFF	Area 18		
	OFF	OFF	ON	ON	OFF	Area 19		
	ON	ON	OFF	ON	OFF	Area 20		
	OFF	ON	OFF	ON	OFF	Area 21		
	ON	OFF	OFF	ON	OFF	Area 22		
	OFF ON	OFF ON	OFF ON	ON OFF	OFF OFF	Area 23		
	OFF	ON	ON	OFF	OFF	Area 24 Area 25		
	ON	OFF	ON	OFF	OFF	Area 26		
	OFF	OFF	ON	OFF	OFF	Area 27		
	ON	ON	OFF	OFF	OFF	Area 28		
	OFF	ON	OFF	OFF	OFF	Area 29		
	ON	OFF	OFF	OFF	OFF	Area 30		
	OFF	OFF	OFF	OFF	OFF	Area 31		
out Response Time	e Input readi	ng fraguene	ev: 1 scan	time (100	msec)			

# 4. Lead cable color and signals

Color	Signal
Black	Output1
White	Output2
White (Blue)	Output3
Orange	Malfunction Output
Gray	Output common minus
Red	Input common plus
Green	Input1
Yellow	Input2
Purple	Input3
White (Yellow)	Input4
White (Purple)	Input5
Brown	+V IN
Blue	-V IN
Yellow (Red)	Serial Input (RXD)
Yellow (Green)	Serial Output (TXD)
Yellow (Black)	Serial Ground (GND)

Note:

- 1. Leave the unused input terminals open or connect to input common plus (red).
- 2. Leave the unused output terminals open or connect to input common minus (gray).
- 3. Colors inside () suggest wires with colored lines on either sides.

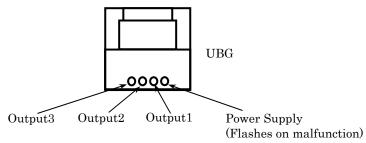
## 5. Installation Notice

When mounting the device make sure to provide sufficient space for light window. Sensor will not operate normally if its view is blocked leading to serious injuries or property damage.

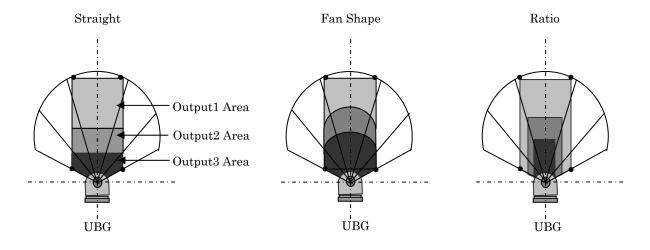
# Note For Long Term Use:

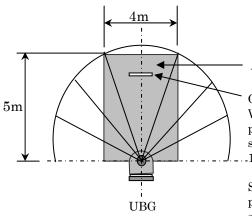
It is necessary to readjust/reset sensors operating for more than one year to maintain the absolute accuracy.

# 6. Light Display Position



# 7. Area Setting Range and Shape





Area Setting Range

# OBJECT:

White Kent sheet 300×300mm placed perpendicular to the sensor's vertical axis within  $-100\sim5000$ mm from sensor axis

Or

Specific Reflector 200×200mm placed perpendicular to the sensor's vertical axis within 100~8000mm form sensor axis

